MATH 260 EXAM #3 Key (Summer 2021)

1a A is a triangular matrix, and so the eigenvalues are immediately seen to be -3, 0, 4.

1b We find a basis for $E_A(4)$, the eigenspace of A corresponding to the largest eigenvalue 4. We have

$$E_A(4) = \{ \mathbf{x} : A\mathbf{x} = 4\mathbf{x} \} = \{ \mathbf{x} : (A - 4I)\mathbf{x} = \mathbf{0} \},\$$

so the job is simply to solve the system $(A - 4I)\mathbf{x} = \mathbf{0}$ to get $\text{Span}\left\{\begin{bmatrix}7 & 0 & 1\end{bmatrix}^{\top}\right\}$, and so $\left\{\begin{bmatrix}7 & 0 & 1\end{bmatrix}^{\top}\right\}$ is a basis.

2 We have $A^2 = O$. Suppose $A\mathbf{x} = \lambda \mathbf{x}$ for some $\mathbf{x} \neq \mathbf{0}$. Then $\mathbf{0} = O\mathbf{x} = A^2\mathbf{x} = A(A\mathbf{x}) = A(A\mathbf{x}) = \lambda(A\mathbf{x}) = \lambda(A\mathbf{x}) = \lambda^2\mathbf{x}$

$$\mathbf{0} = O\mathbf{x} = A \ \mathbf{x} = A(A\mathbf{x}) = A(\lambda\mathbf{x}) = \lambda(A\mathbf{x}) = \lambda(\lambda\mathbf{x}) = \lambda \ \mathbf{x},$$

which implies $\lambda^2 = 0$, and hence $\lambda = 0$. Therefore we conclude that 0 is the only eigenvalue of A.

3 The characteristic equation $det(A - \lambda I) = 0$ becomes $(\lambda - 2)(\lambda - 1) = 12$, which has solutions -2, 5. Since

$$E_A(-2) = \{\mathbf{x} : A\mathbf{x} = -2\mathbf{x}\} = \{\mathbf{x} : (A+2I)\mathbf{x} = \mathbf{0}\} = \operatorname{Span}\left\{ \begin{bmatrix} -3\\4 \end{bmatrix} \right\}$$

and

$$E_A(5) = \{\mathbf{x} : A\mathbf{x} = 5\mathbf{x}\} = \{\mathbf{x} : (A - 5I)\mathbf{x} = \mathbf{0}\} = \operatorname{Span}\left\{\begin{bmatrix}1\\1\end{bmatrix}\right\},\$$

we let

$$D = \begin{bmatrix} -2 & 0 \\ 0 & 5 \end{bmatrix} \quad \text{and} \quad P = \begin{bmatrix} -3 & 1 \\ 4 & 1 \end{bmatrix}.$$

4 For $T(\mathbf{x}) = A\mathbf{x}$ we find $[T]_{\mathcal{B}} = [[T(\mathbf{b}_1)]_{\mathcal{B}} [T(\mathbf{b}_2)]_{\mathcal{B}}]$, where $[T(\mathbf{b}_1)]_{\mathcal{B}} = [x_1]_{\mathcal{B}} = [T(\mathbf{b}_2)]_{\mathcal{B}}$

$$[T(\mathbf{b}_1)]_{\mathcal{B}} = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$
 and $[T(\mathbf{b}_2)]_{\mathcal{B}} = \begin{bmatrix} y_1 \\ y_2 \end{bmatrix}$

with x_1 , x_2 , y_1 , y_2 such that $x_1\mathbf{b}_1 + x_2\mathbf{b}_2 = T(\mathbf{b}_1) = A\mathbf{b}_1$ and $y_1\mathbf{b}_1 + y_2\mathbf{b}_2 = T(\mathbf{b}_2) = A\mathbf{b}_2$. These are two systems of equations having the same coefficient matrix, and we solve both simultaneously:

$$\begin{bmatrix} 3 & -1 & | & 5 & 5 \\ 2 & 1 & | & 0 & 5 \end{bmatrix} \sim \begin{bmatrix} 2 & 1 & | & 0 & 5 \\ 3 & -1 & | & 5 & 5 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & | & 1 & 2 \\ 0 & 1 & | & -2 & 1 \end{bmatrix}.$$

From this we obtain

$$[T]_{\mathcal{B}} = \begin{bmatrix} 1 & 2\\ -2 & 1 \end{bmatrix}.$$

5
$$\mathbf{v}/\|\mathbf{v}\| = \frac{\mathbf{v}}{\sqrt{61}} = \begin{bmatrix} -6/\sqrt{61} \\ 4/\sqrt{61} \\ -3/\sqrt{61} \end{bmatrix}.$$

6
$$\mathbf{x} = \sum_{k=1}^{3} \left(\frac{\mathbf{x} \cdot \mathbf{u}_k}{\mathbf{u}_k \cdot \mathbf{u}_k} \right) \mathbf{u}_k = \frac{5}{2} \mathbf{u}_1 - \frac{3}{2} \mathbf{u}_2 + 2\mathbf{u}_3.$$

7 By a theorem we have $U^{\top}U = I$, and so, for any $\mathbf{x}, \mathbf{y} \in \mathbb{R}^n$, $(U\mathbf{x}) \cdot (U\mathbf{y}) = (U\mathbf{x})^{\top}(U\mathbf{y}) = \mathbf{x}^{\top}U^{\top}U\mathbf{y} = \mathbf{x}^{\top}I\mathbf{y} = \mathbf{x}^{\top}\mathbf{y} = \mathbf{x} \cdot \mathbf{y}.$

8 Let $W = \text{Span}\{\mathbf{u}_1, \mathbf{u}_2\}$. The best approximation is

$$\hat{\mathbf{x}} = \operatorname{proj}_{W} \mathbf{x} = \sum_{k=1}^{2} \left(\frac{\mathbf{x} \cdot \mathbf{u}_{k}}{\mathbf{u}_{k} \cdot \mathbf{u}_{k}} \right) \mathbf{u}_{k} = \frac{1}{14} \begin{bmatrix} 2\\0\\-1\\3 \end{bmatrix} + \frac{4}{49} \begin{bmatrix} 5\\-2\\4\\2 \end{bmatrix} = \begin{bmatrix} 27/49\\-8/49\\25/98\\-5/98 \end{bmatrix}.$$

9 Let

$$\mathbf{u}_{1} = \begin{bmatrix} 3\\1\\-1\\1 \end{bmatrix}, \quad \mathbf{u}_{2} = \begin{bmatrix} -8\\-4\\6\\-2 \end{bmatrix}, \quad \mathbf{u}_{3} = \begin{bmatrix} 3\\-3\\6\\6 \end{bmatrix}.$$

Set $\mathbf{w}_1 = \mathbf{u}_1$. By the Gram-Schmidt procedure,

$$\mathbf{w}_2 = \mathbf{u}_2 - \left(\frac{\mathbf{u}_2 \cdot \mathbf{w}_1}{\mathbf{w}_1 \cdot \mathbf{w}_1}\right) \mathbf{w}_1 = \begin{bmatrix} 1\\ -1\\ 3\\ 1 \end{bmatrix},$$

and

$$\mathbf{w}_3 = \mathbf{u}_3 - \left(\frac{\mathbf{u}_3 \cdot \mathbf{w}_1}{\mathbf{w}_1 \cdot \mathbf{w}_1}\right) \mathbf{w}_1 - \left(\frac{\mathbf{u}_3 \cdot \mathbf{w}_2}{\mathbf{w}_2 \cdot \mathbf{w}_2}\right) \mathbf{w}_2 = \begin{bmatrix} -1\\ -1\\ -1\\ 3 \end{bmatrix}.$$

Orthogonal basis for $\operatorname{Col} \mathbf{A}$ is $\{\mathbf{w}_1, \mathbf{w}_2, \mathbf{w}_3\}$.

10 Best approximation is

$$\hat{p} = \frac{\langle r, p_0 \rangle}{\langle p_0, p_0 \rangle} p_0 + \frac{\langle r, p_1 \rangle}{\langle p_1, p_1 \rangle} p_1 + \frac{\langle r, p_2 \rangle}{\langle p_2, p_2 \rangle} p_2.$$

Now,

$$\langle r, p_0 \rangle = r(-3)p_0(-3) + r(-1)p_0(-1) + r(1)p_0(1) + r(3)p_0(3) = 0,$$

and similarly $\langle r, p_1 \rangle = 164$, $\langle r, p_2 \rangle = 0$, $\langle p_1, p_1 \rangle = 20$. Note we don't need $\langle p_2, p_2 \rangle$. We finally obtain

$$\hat{p}(t) = \frac{164}{20}p_1(t) = \frac{41}{5}t$$

11 Let $\mathbf{u}_1 = 3$, $\mathbf{u}_2 = 2t$, $\mathbf{u}_3 = t^2$. Set $\mathbf{w}_1 = \mathbf{u}_1 = 3$. By the Gram-Schmidt procedure,

$$\mathbf{w}_2 = \mathbf{u}_2 - \frac{\langle \mathbf{u}_2, \mathbf{w}_1 \rangle}{\langle \mathbf{w}_1, \mathbf{w}_1 \rangle} \mathbf{w}_1 = 2t - \frac{\int_{-3}^3 6t \, dt}{\int_{-3}^3 9 \, dt} (3) = 2t,$$

and

$$\mathbf{w}_{3} = \mathbf{u}_{3} - \frac{\langle \mathbf{u}_{3}, \mathbf{w}_{1} \rangle}{\langle \mathbf{w}_{1}, \mathbf{w}_{1} \rangle} \mathbf{w}_{1} - \frac{\langle \mathbf{u}_{3}, \mathbf{w}_{2} \rangle}{\langle \mathbf{w}_{2}, \mathbf{w}_{2} \rangle} \mathbf{w}_{2} = t^{2} - \frac{\int_{-3}^{3} 3t^{2} dt}{\int_{-3}^{3} 9 dt} (3) - \frac{\int_{-3}^{3} 2t^{3} dt}{\int_{-3}^{3} 4t^{2} dt} (2t) = t^{2} - 3.$$

 $\{\mathbf{w}_1,\mathbf{w}_2,\mathbf{w}_3\}$ is an orthogonal basis.