

1 We have:

$$\begin{vmatrix} a & b & c \\ d+4g & e+4h & f+4i \\ g & h & i \end{vmatrix} = -9 \Rightarrow \begin{vmatrix} g & h & i \\ d+4g & e+4h & f+4i \\ a & b & c \end{vmatrix} = 9,$$

and hence

$$\begin{vmatrix} -3g & -3h & -3i \\ d+4g & e+4h & f+4i \\ -2a & -2b & -2c \end{vmatrix} = (-3)(-2)9 = 54.$$

2 Using the property $\det(\mathbf{AB}) = \det(\mathbf{A})\det(\mathbf{B})$,

$$\det(\mathbf{A}^7) = 0 \Rightarrow (\det \mathbf{A})^7 = 0 \Rightarrow \det \mathbf{A} = 0,$$

and so \mathbf{A} is not invertible by the Invertible Matrix Theorem.

3 The system is $\mathbf{Ax} = \mathbf{b}$ with

$$\mathbf{A} = \begin{bmatrix} 1 & 3 & 1 \\ -1 & 0 & 2 \\ 3 & 1 & 0 \end{bmatrix}, \quad \mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}, \quad \mathbf{b} = \begin{bmatrix} 4 \\ 2 \\ 2 \end{bmatrix}.$$

Expanding along the 3rd column we have

$$\det \mathbf{A} = \begin{vmatrix} -1 & 0 \\ 3 & 1 \end{vmatrix} - 2 \begin{vmatrix} 1 & 3 \\ 3 & 1 \end{vmatrix} = -1 - 2(1 - 9) = 15,$$

so $\det \mathbf{A} \neq 0$ and by Cramer's Rule

$$x_1 = \frac{1}{\det \mathbf{A}} \begin{vmatrix} 4 & 3 & 1 \\ 2 & 0 & 2 \\ 2 & 1 & 0 \end{vmatrix} = \frac{1}{15}(6) = \frac{2}{5}$$

$$x_2 = \frac{1}{\det \mathbf{A}} \begin{vmatrix} 1 & 4 & 1 \\ -1 & 2 & 2 \\ 3 & 2 & 0 \end{vmatrix} = \frac{1}{15}(12) = \frac{4}{5}$$

$$x_3 = \frac{1}{\det \mathbf{A}} \begin{vmatrix} 1 & 3 & 4 \\ -1 & 0 & 2 \\ 3 & 1 & 2 \end{vmatrix} = \frac{1}{15}(18) = \frac{6}{5}$$

Therefore the solution to the system is $(\frac{2}{5}, \frac{4}{5}, \frac{6}{5})$.

4 Take the absolute value of the determinant

$$\begin{vmatrix} 1 & -2 & -1 \\ 3 & 0 & 3 \\ 0 & 2 & -1 \end{vmatrix} = \begin{vmatrix} 1 & -2 & -1 \\ 3 & 0 & 3 \\ 1 & 0 & -2 \end{vmatrix} = -18,$$

to get a volume of 18.

5 We find that

$$W = s \begin{bmatrix} 1 \\ 1 \\ 2 \\ 0 \end{bmatrix} + t \begin{bmatrix} 3 \\ -1 \\ -7 \\ 4 \end{bmatrix} = \text{Span} \left\{ \begin{bmatrix} 1 \\ 1 \\ 2 \\ 0 \end{bmatrix}, \begin{bmatrix} 3 \\ -1 \\ -7 \\ 4 \end{bmatrix} \right\},$$

and so W is a subspace of \mathbb{R}^4 by virtue of the fact that it equals the span of two vectors in \mathbb{R}^4 . (See Theorem 1 on p. 196.)

6 Let W denote the set. The zero function on $[a, b]$, which we'll denote here by $\mathbf{0}$, is certainly a continuous real-valued function, and since $\mathbf{0}(a) = 0 = \mathbf{0}(b)$ it follows that $\mathbf{0} \in W$.

Next, suppose $f, g \in W$, so f and g are continuous and real-valued on $[a, b]$ such that $f(a) = f(b)$ and $g(a) = g(b)$. Adding the two equations gives $f(a) + g(a) = f(b) + g(b)$, and thus $(f + g)(a) = (f + g)(b)$, and since calculus informs us that $f + g$ must also be continuous and real-valued on $[a, b]$, we conclude that $f + g \in W$. Therefore W is closed under vector addition.

Finally, for any $f \in W$ and scalar $c \in \mathbb{R}$ we know that cf must be continuous and real-valued, and since $f(a) = f(b) \Rightarrow cf(a) = cf(b) \Rightarrow (cf)(a) = (cf)(b)$, we conclude that $cf \in W$. Therefore W is closed under scalar multiplication. This shows that W is a subspace of $\mathcal{C}[a, b]$.

7 W lacks the zero vector: letting $r = s = t = 0$ gives the falsehood $2 = 0$ in the equation that defines W . This immediately implies W is not a vector space.

8 Let \mathbf{A} be the given matrix. By definition $\text{Nul } \mathbf{A} = \{\mathbf{x} : \mathbf{A}\mathbf{x} = \mathbf{0}\}$, so the job is to find a basis for the solution set to the homogeneous system with augmented matrix

$$\left[\begin{array}{ccccc|c} 1 & 0 & -5 & 1 & 4 & 0 \\ 0 & 1 & -4 & 0 & 6 & 0 \\ 0 & 2 & -8 & 1 & 9 & 0 \end{array} \right] \sim \left[\begin{array}{ccccc|c} 1 & 0 & -5 & 1 & 4 & 0 \\ 0 & 1 & -4 & 0 & 6 & 0 \\ 0 & 0 & 0 & 1 & -3 & 0 \end{array} \right]$$

We find that

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{bmatrix} = \begin{bmatrix} 5x_3 - 7x_5 \\ 4x_3 - 6x_5 \\ x_3 \\ 3x_5 \\ x_5 \end{bmatrix} = x_3 \begin{bmatrix} 5 \\ 4 \\ 1 \\ 0 \\ 0 \end{bmatrix} + x_5 \begin{bmatrix} -7 \\ -6 \\ 0 \\ 3 \\ 1 \end{bmatrix},$$

where x_3 and x_5 are free, and so a basis for $\text{Nul } \mathbf{A}$ is the set

$$\left\{ \begin{bmatrix} 5 \\ 4 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} -7 \\ -6 \\ 0 \\ 3 \\ 1 \end{bmatrix} \right\}.$$

9 Define the matrix $\mathbf{V} = [\mathbf{v}_1 \ \mathbf{v}_2 \ \mathbf{v}_3 \ \mathbf{v}_4 \ \mathbf{v}_5]$, so the space in question is $\text{Col } \mathbf{V}$. With a series of row operations get a new matrix \mathbf{B} that is in echelon form:

$$\mathbf{V} = \begin{bmatrix} 1 & -2 & 6 & 5 & 0 \\ 0 & 1 & -1 & -3 & 3 \\ 0 & -1 & 2 & 3 & -1 \\ 1 & 1 & -1 & -4 & 1 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 0 & -7 & 8 \\ 0 & 1 & 0 & -3 & 5 \\ 0 & 0 & 1 & 0 & 2 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} = \mathbf{B}.$$

The last two columns of \mathbf{B} can each be expressed as linear combinations of the first three columns, so can be discarded. The same relationship must hold for the columns of \mathbf{V} , so any basis for $\text{Col } \mathbf{V}$ must involve only $\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3$ (i.e. the first three columns of \mathbf{V}). But the first three columns of \mathbf{V} must be linearly independent since the first three columns of \mathbf{B} are. Thus $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$ is a linearly independent set that spans $\text{Col } \mathbf{V}$, and therefore forms a basis for the space in question.

10 This one is easy, since the columns of the matrix are given:

$$P_{\mathcal{B}} = \begin{bmatrix} 3 & 2 & 8 \\ -1 & 0 & -2 \\ 4 & -5 & 7 \end{bmatrix}.$$

11 Let $\mathbf{b}_1(t) = 1 - t^2$, $\mathbf{b}_2(t) = t - t^2$, and $\mathbf{b}_3(t) = 2 - 2t + t^2$. We must find scalars c_1, c_2, c_3 such that $c_1\mathbf{b}_1 + c_2\mathbf{b}_2 + c_3\mathbf{b}_3 = \mathbf{p}(t)$. Collecting terms, this gives

$$(c_1 + 2c_3) + (c_2 - 2c_3)t + (-c_1 - c_2 + c_3)t^2 = 3 + t - 6t^2.$$

Matching coefficients, we obtain the system

$$\begin{cases} -c_1 - c_2 + c_3 = -6 \\ c_2 - 2c_3 = 1 \\ c_1 + 2c_3 = 3 \end{cases}$$

which has solution $(c_1, c_2, c_3) = (7, -3, -2)$. Therefore

$$[\mathbf{p}(t)]_{\mathcal{B}} = \begin{bmatrix} c_1 \\ c_2 \\ c_3 \end{bmatrix} = \begin{bmatrix} 7 \\ -3 \\ -2 \end{bmatrix}.$$

12 See the discussion on page 230 of the text: since \mathbf{A} is already in echelon form, the dimension of the null space of \mathbf{A} equals the number of nonpivot columns, while the dimension of the column space of \mathbf{A} equals the number of pivot columns. Hence $\text{Nul } \mathbf{A} = 3$ and $\text{Col } \mathbf{A} = 3$.

Alternatively: for $m \times n$ matrix \mathbf{A} use the Rank Theorem on page 235, which states that

$$\dim \text{Col } \mathbf{A} + \dim \text{Nul } \mathbf{A} = n.$$

13 Polynomial functions are continuous on \mathbb{R} , so each polynomial vector space \mathbb{P}_n is a subspace of the vector space $\mathcal{C}(\mathbb{R})$. Thus, if $\mathcal{C}(\mathbb{R})$ were a finite-dimensional vector space, then by Theorem

11 on page 229 of the text the dimension of $\mathcal{C}(\mathbb{R})$ must be greater than or equal to the dimension of each \mathbb{P}_n , which is $n + 1$. That is, if $\mathcal{C}(\mathbb{R})$ were finite-dimensional, then $\dim \mathcal{C}(\mathbb{R}) \geq n + 1$ for each integer $n \geq 0$, and we would conclude that $\dim \mathcal{C}(\mathbb{R})$ has no upper bound, as with the set of integers. This is a contradiction. Therefore $\mathcal{C}(\mathbb{R})$ must be infinite-dimensional.

14 Let \mathbf{A} be $m \times n$ with $m > n$ (i.e. a matrix with more rows than columns). Clearly $\dim \text{Col } \mathbf{A} \leq n$ and $\dim \text{Row } \mathbf{A} \leq m$ must hold, but by the Rank Theorem (p. 235),

$$\text{rank } \mathbf{A} = \dim \text{Col } \mathbf{A} = \dim \text{Row } \mathbf{A},$$

so since $n < m$ we conclude that \mathbf{A} can have full rank if and only if $\dim \text{Col } \mathbf{A} = n$. To finish the argument we now just need to prove that $\dim \text{Col } \mathbf{A} = n$ if and only if the columns of \mathbf{A} are linearly independent.

Suppose $\dim \text{Col } \mathbf{A} = n$. Because $\text{Col } \mathbf{A}$ is the span of the n columns of \mathbf{A} , we conclude by the Basis Theorem (p. 229) that the columns of \mathbf{A} are linearly independent.

For the converse, suppose the columns of \mathbf{A} are linearly independent. Then the n columns of \mathbf{A} form a basis for $\text{Col } \mathbf{A}$ by the Basis Theorem, implying $\dim \text{Col } \mathbf{A} = n$.

15 First we get $P_{\mathcal{C} \leftarrow \mathcal{B}} = [[\mathbf{b}_1]_{\mathcal{C}} \quad [\mathbf{b}_2]_{\mathcal{C}}]$. To find $[\mathbf{b}_1]_{\mathcal{C}}$ we find scalars x_1, x_2 such that $x_1 \mathbf{c}_1 + x_2 \mathbf{c}_2 = \mathbf{b}_1$, which is a system with augmented matrix

$$\begin{bmatrix} 1 & 1 & -1 \\ 4 & 1 & 8 \end{bmatrix}.$$

Solving gives $x_1 = 3$ and $x_2 = -4$. To find $[\mathbf{b}_2]_{\mathcal{C}}$ we find y_1, y_2 such that $y_1 \mathbf{c}_1 + y_2 \mathbf{c}_2 = \mathbf{b}_2$, which is a system with augmented matrix

$$\begin{bmatrix} 1 & 1 & 1 \\ 4 & 1 & -5 \end{bmatrix}.$$

Solving gives $y_1 = -2$ and $y_2 = 3$. Therefore

$$P_{\mathcal{C} \leftarrow \mathcal{B}} = [[\mathbf{b}_1]_{\mathcal{C}} \quad [\mathbf{b}_2]_{\mathcal{C}}] = \begin{bmatrix} 3 & -2 \\ -4 & 3 \end{bmatrix} \quad \text{and} \quad P_{\mathcal{B} \leftarrow \mathcal{C}} = P_{\mathcal{C} \leftarrow \mathcal{B}}^{-1} = \begin{bmatrix} 3 & 2 \\ 4 & 3 \end{bmatrix}.$$