MATH 260 EXAM #2 KEY (SUMMER 2015)

1 Supposing $\mathbf{u} + \mathbf{w} = \mathbf{v} + \mathbf{w}$, we obtain $(\mathbf{u} + \mathbf{w}) + (-\mathbf{w}) = (\mathbf{v} + \mathbf{w}) + (-\mathbf{w})$, so that $\mathbf{u} + (\mathbf{w} + (-\mathbf{w})) = \mathbf{v} + (\mathbf{w} + (-\mathbf{w}))$ by VS2, then $\mathbf{u} + \mathbf{0} = \mathbf{v} + \mathbf{0}$ by VS4, and finally $\mathbf{u} = \mathbf{v}$ by VS3.

2 Consider $\mathbf{u} = [1, 0, 0]^{\top}$ and $\mathbf{v} = [0, 1, 0]^{\top}$. We have $\|\mathbf{u}\| = 1 = 1 + 0 = |u_1| + |u_2|$ and $\|\mathbf{v}\| = 1 = 0 + 1 = |v_1| + |v_2|$, so $\mathbf{u}, \mathbf{v} \in U$. But $\mathbf{w} = \mathbf{u} + \mathbf{v} = [1, 1, 0]^{\top}$, so that

$$\|\mathbf{w}\| = \sqrt{1^2 + 1^2 + 0^2} = \sqrt{2} \neq 2 = |w_1| + |w_2|,$$

which shows that $\mathbf{u} + \mathbf{v} = \mathbf{w} \notin U$. Hence U is not closed under vector addition and cannot be a subspace.

3 We must find $x_1, x_2, x_3 \in \mathbb{R}$ such that $x_1\mathbf{u}_1 + x_2\mathbf{u}_2 + x_3\mathbf{u}_3 = \mathbf{v}$, if possible. This gives us the system

$$\begin{cases} 4x_1 + 4x_2 + x_3 = 7 \\ 2x_1 - 3x_2 + 3x_3 = 16 \\ x_1 + 2x_2 - x_3 = -3 \end{cases}$$

This system has the unique solution $(x_1, x_2, x_3) = (2, -1, 3)$.

4a We can do elementary column operations on **A** to get the column rank (and hence the rank) of the matrix:

$$\mathbf{A} \xrightarrow[-c_1+c_3\to c_3]{1} \begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 2 \\ 0 & 2 & 4 \end{bmatrix} \xrightarrow{-2c_2+c_3\to c_3} \begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ 0 & 2 & 0 \end{bmatrix}.$$

We now see that $rank(\mathbf{A}) = 2$, and since column operations do not alter a column space, we also have a basis for $Col(\mathbf{A})$:

$$\left\{ \begin{bmatrix} 1\\1\\0 \end{bmatrix}, \begin{bmatrix} 0\\1\\2 \end{bmatrix} \right\}.$$

But it is quick to verify that the first two columns of **A** are linearly independent, and since we now know that $rank(\mathbf{A}) = 2$ it follows that they also constitute a basis for $Col(\mathbf{A})$:

$$\left\{ \begin{bmatrix} 1\\1\\0 \end{bmatrix}, \begin{bmatrix} 2\\3\\2 \end{bmatrix} \right\}.$$

Other bases are possible.

4b By definition $Nul(\mathbf{A}) = \{\mathbf{x} \in \mathbb{R}^3 : \mathbf{A}\mathbf{x} = \mathbf{0}\}$, otherwise known as the solution set of the system

$$\begin{cases} x_1 + 2x_2 + x_3 = 0 \\ x_1 + 3x_2 + 3x_3 = 0 \\ 2x_2 + 4x_3 = 0 \end{cases}$$

This system is equivalent to

$$\begin{cases} x_1 + 2x_2 + x_3 = 0 \\ x_2 + 2x_3 = 0 \\ x_2 + 2x_3 = 0 \end{cases}$$

From this we obtain $x_2 = -2x_3$ and $x_1 = 3x_3$, and hence

$$\operatorname{Nul}(\mathbf{A}) = \left\{ \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} : x_1 = 3x_3, \ x_2 = -2x_3 \right\} = \left\{ t \begin{bmatrix} 3 \\ -2 \\ 1 \end{bmatrix} : t \in \mathbb{R} \right\}.$$

This shows that $[3, -2, 1]^{\top}$ is a basis for Nul(**A**). Any nonzero scalar multiple of this vector will also work.

5 Suppose that $\mathbf{x} \in \text{Nul}(\mathbf{B})$, so that $\mathbf{B}\mathbf{x} = \mathbf{0}$. Recalling that matrix multiplication is associative, we find that

$$(\mathbf{A}\mathbf{B})\mathbf{x} = \mathbf{A}(\mathbf{B}\mathbf{x}) = \mathbf{A}\mathbf{0} = \mathbf{0},$$

which shows $\mathbf{x} \in \text{Nul}(\mathbf{AB})$. Hence $\text{Nul}(\mathbf{B}) \subseteq \text{Nul}(\mathbf{AB})$.

Now suppose that $\mathbf{x} \in \text{Nul}(\mathbf{AB})$, so that $(\mathbf{AB})\mathbf{x} = \mathbf{0}$. Now, since \mathbf{A} is invertible, we find that

$$(\mathbf{A}\mathbf{B})\mathbf{x} = \mathbf{0} \ \Rightarrow \ \mathbf{A}^{-1}(\mathbf{A}\mathbf{B})\mathbf{x} = \mathbf{A}^{-1}\mathbf{0} \ \Rightarrow \ (\mathbf{A}^{-1}\mathbf{A})\mathbf{B}\mathbf{x} = \mathbf{0} \ \Rightarrow \ \mathbf{B}\mathbf{x} = \mathbf{0},$$

which shows $\mathbf{x} \in \text{Nul}(\mathbf{B})$. Hence $\text{Nul}(\mathbf{AB}) \subseteq \text{Nul}(\mathbf{B})$, and therefore $\text{Nul}(\mathbf{AB}) = \text{Nul}(\mathbf{B})$.

6 The top row of \mathbf{C} has nonzero first component while the bottom row has first component equal to zero, which means the two row vectors are linearly independent and the dimension of $\operatorname{Row}(\mathbf{C})$ is 2. Thus the dimension of $\operatorname{Col}(\mathbf{C})$ must also be 2. Since $\operatorname{rank}(\mathbf{C}) = 2$ and the Rank-Nullity Theorem informs us that $\operatorname{rank}(\mathbf{C}) + \operatorname{nullity}(\mathbf{C}) = 5$, we find that $\operatorname{nullity}(\mathbf{C}) = 3$. That is, the dimension of $\operatorname{Nul}(\mathbf{C})$ is 3.

7a Letting $\mathbf{e}_1 = [1, 0]^{\mathsf{T}}$ and $\mathbf{e}_2 = [0, 1]^{\mathsf{T}}$, by an established theorem we have

$$\mathbf{I}_{\mathcal{EB}} = \begin{bmatrix} [\mathbf{e}_1]_{\mathcal{B}} & [\mathbf{e}_2]_{\mathcal{B}} \end{bmatrix},$$

and so we must find the \mathcal{B} -coordinates of \mathbf{e}_1 and \mathbf{e}_2 . Letting $\mathbf{b}_1 = [1, 2]^{\top}$ and $\mathbf{b}_2 = [-2, 1]^{\top}$, so that $\mathcal{B} = (\mathbf{b}_1, \mathbf{b}_2)$, we must find $x_1, x_2, y_1, y_2 \in \mathbb{R}$ so $x_1\mathbf{b}_1 + x_2\mathbf{b}_2 = \mathbf{e}_1$ and $y_1\mathbf{b}_1 + y_2\mathbf{b}_2 = \mathbf{e}_2$; that is,

$$\begin{cases} x_1 - 2x_2 = 1 \\ 2x_1 + x_2 = 0 \end{cases} \text{ and } \begin{cases} y_1 - 2y_2 = 0 \\ 2y_1 + y_2 = 1 \end{cases}$$

Solving these systems gives $(x_1, x_2) = (\frac{1}{5}, -\frac{2}{5})$ and $(y_1, y_2) = (\frac{2}{5}, \frac{1}{5})$. Thus $[\mathbf{e}_1]_{\mathcal{B}} = [\frac{1}{5}, -\frac{2}{5}]^{\top}$ and $[\mathbf{e}_2]_{\mathcal{B}} = [\frac{2}{5}, \frac{1}{5}]^{\top}$, and we obtain

$$\mathbf{I}_{\mathcal{EB}} = \begin{bmatrix} \frac{1}{5} & \frac{2}{5} \\ -\frac{2}{5} & \frac{1}{5} \end{bmatrix}.$$

7b We have

$$[\mathbf{x}]_{\mathcal{B}} = \mathbf{I}_{\mathcal{E}\mathcal{B}}[\mathbf{x}]_{\mathcal{E}} = \begin{bmatrix} \frac{1}{5} & \frac{2}{5} \\ -\frac{2}{5} & \frac{1}{5} \end{bmatrix} \begin{bmatrix} 2 \\ -5 \end{bmatrix} = \begin{bmatrix} -\frac{8}{5} \\ -\frac{9}{5} \end{bmatrix}.$$

8a Let [L] denote the matrix corresponding to L with respect to the standard bases for \mathbb{R}^2 and \mathbb{R}^3 . Setting

$$\mathbf{B} = \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix},$$

we have

$$[L]\mathbf{B} = \begin{bmatrix} [L] \begin{bmatrix} 1 \\ 1 \end{bmatrix} & [L] \begin{bmatrix} 1 \\ -1 \end{bmatrix} \end{bmatrix} = \begin{bmatrix} 1 & 1 \\ 1 & -1 \\ 1 & -1 \end{bmatrix}. \tag{1}$$

The square matrix \mathbf{B} has linearly independent columns and so is invertible. Right-multiplying through (1) by \mathbf{B}^{-1} gives

$$[L] = \begin{bmatrix} 1 & 1 \\ 1 & -1 \\ 1 & -1 \end{bmatrix} \mathbf{B}^{-1} = \begin{bmatrix} 1 & 1 \\ 1 & -1 \\ 1 & -1 \end{bmatrix} \begin{bmatrix} \frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & -\frac{1}{2} \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 1 \end{bmatrix}.$$

8b We have

$$L\left(\begin{bmatrix} x \\ y \end{bmatrix}\right) = [L] \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} x \\ y \\ y \end{bmatrix}.$$

8c The range (i.e. image) of L is

$$\operatorname{Img}(L) = \left\{ \begin{bmatrix} s \\ t \\ t \end{bmatrix} : s, t \in \mathbb{R} \right\} = \left\{ s \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + t \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} : s, t \in \mathbb{R} \right\},$$

which is Col([L]) as to be expected, and happens to be the plane y=z in \mathbb{R}^3 .

The kernel (i.e. null space) of L is

$$\operatorname{Nul}(L) = \left\{ \begin{bmatrix} x \\ y \end{bmatrix} \in \mathbb{R}^2 : L\left(\begin{bmatrix} x \\ y \end{bmatrix} \right) = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \right\} = \left\{ \begin{bmatrix} x \\ y \end{bmatrix} \in \mathbb{R}^2 : \begin{bmatrix} x \\ y \\ y \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \right\} = \left\{ \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \right\}.$$

Thus the kernel of L is trivial, which straightaway implies that L is one-to-one.