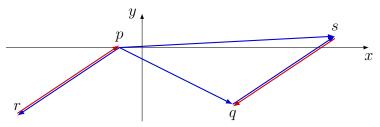
MATH 260 EXAM #1 KEY (SUMMER 2012)

1. Quite trivially we have

$$3p = 3(3, -1, 8) = (9, -3, 24),$$

 $p + q = (3, -1, 8) + (-2, -9, 0) = (1, -10, 8),$
 $p - 2q = (3, -1, 8) - 2(-2, -9, 0) = (7, 17, 8).$

2. We have $\vec{rp} \sim \vec{qs}$ since p - r = (-2, 0) - (-11, -6) = (9, 6) = (17, 1) - (8, -5) = s - q. Also $\vec{pr} \sim \vec{sq}$.



3. Since $\mathbf{u} \in \mathbb{R}^n$ we have $\mathbf{u} = \langle u_1, \dots, u_n \rangle$. For each $1 \leq i \leq n$ let $\mathbf{e}_i = \langle 0, \dots, 1, \dots, 0 \rangle$, the vector with *i*th coordinate 1 and all other coordinates 0. Since \mathbf{u} is orthogonal to all vectors in \mathbb{R}^n , we have

$$u_i = (u_1)(0) + (u_2)(0) + \dots + (u_i)(1) + \dots + (u_n)(0) = \mathbf{u} \cdot \mathbf{e}_i = 0$$

for all i. Thus $\mathbf{u} = \mathbf{0}$.

4a.
$$|\mathbf{u}| = \sqrt{2^2 + (-1)^2 + 5^2} = \sqrt{30}$$
 and $|\mathbf{v}| = \sqrt{(-1)^2 + 1^2 + 1^2} = \sqrt{3}$.

4b. Since
$$\mathbf{u} \cdot \mathbf{v} = (2)(-1) + (-1)(1) + (5)(1) = 2$$
 and $\mathbf{v} \cdot \mathbf{v} = |\mathbf{v}|^2 = (\sqrt{3})^2 = 3$, we have $\operatorname{proj}_{\mathbf{v}} \mathbf{u} = \left(\frac{\mathbf{u} \cdot \mathbf{v}}{\mathbf{v} \cdot \mathbf{v}}\right) \mathbf{v} = \frac{2}{3} \langle -1, 1, 1 \rangle = \left\langle -\frac{2}{3}, \frac{2}{3}, \frac{2}{3} \right\rangle$.

4c. We have

$$\cos\theta = \frac{\mathbf{u} \cdot \mathbf{v}}{|\mathbf{u}||\mathbf{v}|} = \frac{2}{\sqrt{30}\sqrt{3}} = \frac{2}{3\sqrt{10}} \quad \Rightarrow \quad \theta = \cos^{-1}\left(\frac{2}{3\sqrt{10}}\right) \approx 77.8^{\circ}.$$

5a. The easiest 10 points you could hope for:

$$\mathbf{A}^T = \begin{bmatrix} 2 & -1 \\ -3 & 4 \\ 0 & 6 \end{bmatrix}$$

5b. We have

$$\mathbf{AB} = \begin{bmatrix} -14 & 7 \\ 25 & -55 \end{bmatrix}$$

6. We have $A^2 = AA$, $A^3 = AA^2$, $A^4 = AA^3$, so

$$\mathbf{A}^2 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 4 & 0 \\ 0 & 0 & 9 \end{bmatrix}, \quad \mathbf{A}^3 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 3 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 4 & 0 \\ 0 & 0 & 9 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 8 & 0 \\ 0 & 0 & 27 \end{bmatrix}, \quad \mathbf{A}^4 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 16 & 0 \\ 0 & 0 & 81 \end{bmatrix}.$$

7. We must find a 2×2 matrix with entries a, b, c, and d such that

$$\begin{bmatrix} \cos\theta & -\sin\theta \\ \sin\theta & \cos\theta \end{bmatrix} \begin{bmatrix} a & b \\ c & d \end{bmatrix} = \begin{bmatrix} a\cos\theta - c\sin\theta & b\cos\theta - d\sin\theta \\ a\sin\theta + c\cos\theta & b\sin\theta + d\cos\theta \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}.$$

To get $a\cos\theta - c\sin\theta = 1$, let $a = \cos\theta$ and $c = -\sin\theta$; to get $b\cos\theta - d\sin\theta = 0$ let $b = \sin\theta$ and $d = \cos\theta$. It can be seen that these choices work, and moreover

$$\begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

also holds for these choices. Thus, the inverse of \mathbf{R}_{θ} is

$$\mathbf{R}_{\theta}^{-1} = \begin{bmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{bmatrix}.$$

8. From the second equation we have y = -x. Putting this into the first and third equations gives 11x + 3z = 0 and x + 6z = 0. From the latter equation comes x = -6z, which when put into the former equation yields 11(-6z) + 3z = 0, and thus z = 0. Since z = 0, we get x = -6(0) = 0, and then y = -0 = 0. That is, x = y = z = 0 is the only solution.

9. Call the matrix **A**. Then,

$$\mathbf{A} \xrightarrow{r_1 \leftrightarrow r_2} \begin{bmatrix} 2 & 1 & -4 & 3 \\ 0 & 1 & 3 & -2 \\ 2 & 3 & 2 & -1 \end{bmatrix} \xrightarrow{-r_1 + r_3 \to r_3} \begin{bmatrix} 2 & 1 & -4 & 3 \\ 0 & 1 & 3 & -2 \\ 0 & 2 & 6 & -4 \end{bmatrix} \xrightarrow{-2r_2 + r_3 \to r_3} \begin{bmatrix} 2 & 1 & -4 & 3 \\ 0 & 1 & 3 & -2 \\ 0 & 0 & 0 & 0 \end{bmatrix}.$$

10. Letting A be the matrix, we have

$$\begin{bmatrix} 2 & 4 & 3 & 1 & 0 & 0 \\ -1 & 3 & 0 & 0 & 1 & 0 \\ 0 & 2 & 1 & 0 & 0 & 1 \end{bmatrix} \xrightarrow{r_2 \leftrightarrow r_1} \begin{bmatrix} 1 & -3 & 0 & 0 & -1 & 0 \\ 2 & 4 & 3 & 1 & 0 & 0 \\ 0 & 2 & 1 & 0 & 0 & 1 \end{bmatrix} \xrightarrow{-2r_1 + r_2 \to r_2} \begin{bmatrix} 1 & -3 & 0 & 0 & -1 & 0 \\ 0 & 10 & 3 & 1 & 2 & 0 \\ 0 & 2 & 1 & 0 & 0 & 1 \end{bmatrix}$$

$$\xrightarrow{r_2 \leftrightarrow r_3} \begin{bmatrix} 1 & -3 & 0 & 0 & -1 & 0 \\ 0 & 2 & 1 & 0 & 0 & 1 \\ 0 & 10 & 3 & 1 & 2 & 0 \end{bmatrix} \xrightarrow{-5r_2 + r_3 \to r_3} \begin{bmatrix} 1 & -3 & 0 & 0 & -1 & 0 \\ 0 & 2 & 1 & 0 & 0 & 1 \\ 0 & 0 & -2 & 1 & 2 & -5 \end{bmatrix} \xrightarrow{\frac{1}{2}r_2 \to r_2}$$

$$\begin{bmatrix}
1 & -3 & 0 & 0 & -1 & 0 \\
0 & 1 & \frac{1}{2} & 0 & 0 & \frac{1}{2} \\
0 & 0 & -2 & 1 & 2 & -5
\end{bmatrix}
\xrightarrow{3r_2+r_1\to r_1}
\begin{bmatrix}
1 & 0 & \frac{3}{2} & 0 & -1 & \frac{3}{2} \\
0 & 1 & \frac{1}{2} & 0 & 0 & \frac{1}{2} \\
0 & 0 & -2 & 1 & 2 & -5
\end{bmatrix}
\xrightarrow{\frac{1}{4}r_3+r_2\to r_2}
\xrightarrow{\frac{3}{4}r_3+r_1\to r_1}$$

$$\begin{bmatrix}
1 & 0 & 0 & \frac{3}{4} & \frac{1}{2} & -\frac{9}{4} \\
0 & 1 & 0 & \frac{1}{4} & \frac{1}{2} & -\frac{3}{4} \\
0 & 0 & -2 & 1 & 2 & -5
\end{bmatrix}
\xrightarrow{-\frac{1}{2}r_3\to r_3}
\begin{bmatrix}
1 & 0 & 0 & \frac{3}{4} & \frac{1}{2} & -\frac{9}{4} \\
0 & 1 & 0 & \frac{1}{4} & \frac{1}{2} & -\frac{3}{4} \\
0 & 0 & 1 & -\frac{1}{2} & -1 & \frac{5}{2}
\end{bmatrix}.$$

Thus

$$\mathbf{A}^{-1} = \begin{bmatrix} \frac{3}{4} & \frac{1}{2} & -\frac{9}{4} \\ \frac{1}{4} & \frac{1}{2} & -\frac{3}{4} \\ -\frac{1}{2} & -1 & \frac{5}{2} \end{bmatrix}$$

11. V is not a vector space: it lacks O, so A3 fails. Define matrices

$$\mathbf{A} = \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix} \quad \text{and} \quad \mathbf{B} = \begin{bmatrix} 2 & 0 \\ 1 & 3 \end{bmatrix},$$

both of which are in V. A4 and the closure property of scalar multiplication fail since $-\mathbf{A}$ is not in V. The closure property of addition fails since $\mathbf{A} + \mathbf{B} \notin V$.

12. Let $W = \{(x, y) : x + 4y = 0\}$. We show that W is a subspace of \mathbb{R}^2 . Since 0 + 4(0) = 0, we have $(0, 0) \in W$. Next, if $(a, b), (c, d) \in W$ so that a + 4b = 0 and c + 4d = 0, it's clear to see that $(a + c, b + d) \in W$ since

$$(a+c) + 4(b+d) = (a+4b) + (c+4d) = 0 + 0 = 0.$$

Finally, $s(a, b) \in W$ for any $s \in \mathbb{R}$ since s(a, b) = (sa, sb), and sa + 4(sb) = s(a + 4b) = s(0) = 0. Therefore W is a subspace.

13. By definition $U + W = \{\mathbf{u} + \mathbf{w} : \mathbf{u} \in U \text{ and } \mathbf{w} \in W\}$. Since U and W are subspaces we have $\mathbf{0} \in U$ and $\mathbf{0} \in W$, and therefore $\mathbf{0} = \mathbf{0} + \mathbf{0} \in U + W$.

Let $a \in \mathbb{R}$, and suppose that $\mathbf{x} \in U + W$. Then $\mathbf{x} = \mathbf{u} + \mathbf{w}$ for some $\mathbf{u} \in U$ and $\mathbf{w} \in W$, and since U and W are subspaces we also have $a\mathbf{u} \in U$ and $a\mathbf{w} \in W$. Now we find that $a\mathbf{x} \in U + W$ since $a\mathbf{x} = a(\mathbf{u} + \mathbf{w}) = a\mathbf{u} + a\mathbf{w}$.

Finally, let $\mathbf{x}, \mathbf{y} \in U + W$. Then $\mathbf{x} = \mathbf{u}_1 + \mathbf{w}_1$ and $\mathbf{y} = \mathbf{u}_2 + \mathbf{w}_2$ for some $\mathbf{u}_1, \mathbf{u}_2 \in U$ and $\mathbf{w}_1, \mathbf{w}_2 \in W$. Now

$$\mathbf{x} + \mathbf{y} = (\mathbf{u}_1 + \mathbf{w}_1) + (\mathbf{u}_2 + \mathbf{w}_2) = (\mathbf{u}_1 + \mathbf{u}_2) + (\mathbf{w}_1 + \mathbf{w}_2),$$

and since $\mathbf{u}_1 + \mathbf{u}_2 \in U$ and $\mathbf{w}_1 + \mathbf{w}_2 \in W$ it follows that $\mathbf{x} + \mathbf{y} \in U + W$. Therefore U + W is a subspace of V.

14a. Let $\langle a, b, c \rangle \in \mathbb{R}^3$. We attempt to find scalars $x, y, z \in \mathbb{R}$ such that

$$x\langle 1,1,1\rangle + y\langle 2,2,0\rangle + z\langle 3,0,0\rangle = \langle a,b,c\rangle.$$

This yields the system

$$\begin{cases} x + 2y + 3z = a \\ x + 2y = b \\ x = c \end{cases}$$

which indeed has a solution:

$$(x,y,z) = \left(c, \frac{b-c}{2}, \frac{a-b}{3}\right).$$

Thus every vector in \mathbb{R}^3 is expressible as a linear combination of \mathbf{v}_1 , \mathbf{v}_2 , and \mathbf{v}_3 , which shows that the set $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$ spans \mathbb{R}^3 .

14b. Let $\langle a, b, c \rangle \in \mathbb{R}^3$. We attempt to find scalars $x, y, z \in \mathbb{R}$ such that

$$x\langle 2, -1, 3\rangle + y\langle 4, 1, 2\rangle + z\langle 8, -1, 8\rangle = \langle a, b, c\rangle.$$

This yields the system

$$\begin{cases} 2x + 4y + 8z = a \\ -x + y - z = b \\ 3x + 2y + 8z = c \end{cases}$$

This can be cast as an augmented matrix and manipulated using elementary row operations:

$$\begin{bmatrix} 2 & 4 & 8 & | & a \\ -1 & 1 & -1 & | & b \\ 3 & 2 & 8 & | & c \end{bmatrix} \sim \begin{bmatrix} -1 & 1 & -1 & | & b \\ 2 & 4 & 8 & | & a \\ 3 & 2 & 8 & | & c \end{bmatrix} \sim \begin{bmatrix} -1 & 1 & -1 & | & b \\ 0 & 6 & 6 & | & 2b+a \\ 0 & 5 & 5 & | & 3b+c \end{bmatrix}$$
$$\sim \begin{bmatrix} 1 & -1 & 1 & | & -b \\ 0 & 1 & 1 & | & \frac{2b+a}{6} \\ 0 & 5 & 5 & | & 3b+c \end{bmatrix} \sim \begin{bmatrix} 1 & -1 & 1 & | & -b \\ 0 & 1 & 1 & | & \frac{2b+a}{6} \\ 0 & 0 & 0 & | & 3b+c-5 \left(\frac{2b+a}{6}\right) \end{bmatrix}$$

We see that in order for $\langle a, b, c \rangle$ to be expressed as a linear combination of \mathbf{v}_1 , \mathbf{v}_2 , and \mathbf{v}_3 , we need a, b, and c such that

$$3b + c - 5\left(\frac{2b+a}{6}\right) = 0,$$
$$-\frac{5}{6}a + \frac{4}{3}b + c = 0.$$

or

This leads to 1 = 0 if we choose $\langle a, b, c \rangle$ to be $\langle 0, 0, 1 \rangle$, for instance. That is, we cannot express $\langle 0, 0, 1 \rangle$ (among many other vectors) as a linear combination of \mathbf{v}_1 , \mathbf{v}_2 , and \mathbf{v}_3 . We conclude that $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$ does not span \mathbb{R}^3 .