1a Since 5 - 2(7) + 3(3) = 0, we see that (x, y, z) = (5, 7, 3) is a solution to x - 2y + 3z = 0, and hence $\mathbf{v} \in W$. To find the \mathcal{B} -coordinates of \mathbf{v} , we find $a, b \in \mathbb{R}$ such that

$$a\begin{bmatrix}-1\\1\\1\end{bmatrix}+b\begin{bmatrix}1\\2\\1\end{bmatrix}=\begin{bmatrix}5\\7\\3\end{bmatrix},$$

which is to say we solve the system

$$\begin{cases} -a + b = 5\\ a + 2b = 7\\ a + b = 3 \end{cases}$$

The only solution is (a, b) = (-1, 4), and therefore

$$[\mathbf{v}]_{\mathcal{B}} = \begin{bmatrix} -1\\4 \end{bmatrix}.$$

1b Letting $\mathbf{u}_1 = [-1 \ 1 \ 1]^\top$ and $\mathbf{u}_2 = [1 \ 2 \ 1]^\top$, by an established theorem we have

$$\mathbf{M} = \Big[[\mathbf{u}_1]_{\mathcal{C}} \ [\mathbf{u}_2]_{\mathcal{C}} \Big],$$

and so we must find the C-coordinates of \mathbf{u}_1 and \mathbf{u}_2 . Starting with \mathbf{u}_1 , we find $a, b \in \mathbb{R}$ such that $a\mathbf{v}_1 + b\mathbf{v}_2 = \mathbf{u}_1$; that is,

$$a\begin{bmatrix}2\\1\\0\end{bmatrix}+b\begin{bmatrix}-3\\0\\1\end{bmatrix}=\begin{bmatrix}-1\\1\\1\end{bmatrix},$$

v solution and hence

which has (a, b) = (1, 1) as the only solution, and hence

$$[\mathbf{u}_1]_{\mathcal{C}} = \begin{bmatrix} 1\\1 \end{bmatrix}.$$

Next, we find $a, b \in \mathbb{R}$ such that $a\mathbf{v}_1 + b\mathbf{v}_2 = \mathbf{u}_2$; that is,

$$a\begin{bmatrix}2\\1\\0\end{bmatrix}+b\begin{bmatrix}-3\\0\\1\end{bmatrix}=\begin{bmatrix}1\\2\\1\end{bmatrix},$$

which has (a, b) = (2, 1) as the only solution, and hence

$$[\mathbf{u}_2]_{\mathcal{C}} = \begin{bmatrix} 2\\1 \end{bmatrix}.$$

Therefore

$$\mathbf{M} = \begin{bmatrix} 1 & 2 \\ 1 & 1 \end{bmatrix}.$$

1c Using the \mathcal{B} -coordinates of **v** found above, we have

$$[\mathbf{v}]_{\mathcal{C}} = \mathbf{M}[\mathbf{v}]_{\mathcal{B}} = \begin{bmatrix} 1 & 2\\ 1 & 1 \end{bmatrix} \begin{bmatrix} -1\\ 4 \end{bmatrix} = \begin{bmatrix} 7\\ 3 \end{bmatrix}.$$

2 We have $\mathcal{B} = (\mathbf{v}_1, \mathbf{v}_2)$, and $\mathcal{C} = (\mathbf{w}_1, \mathbf{w}_2, \mathbf{w}_3)$. Now,

$$L(\mathbf{v}_1) = L\left(\begin{bmatrix} 3\\1 \end{bmatrix} \right) = \begin{bmatrix} 1\\-5(3)+13(1)\\-7(3)+16(1) \end{bmatrix} = \begin{bmatrix} 1\\-2\\-5 \end{bmatrix}.$$

We need the C-coordinates of $L(\mathbf{v}_1)$, which means finding a_1, a_2, a_3 such that

$$a_1 \mathbf{w}_1 + a_2 \mathbf{w}_2 + a_3 \mathbf{w}_3 = a_1 \begin{bmatrix} 1\\0\\-1 \end{bmatrix} + a_2 \begin{bmatrix} -1\\2\\2 \end{bmatrix} + a_3 \begin{bmatrix} 0\\1\\2 \end{bmatrix} = L(\mathbf{v}_1);$$

that is,

$$\begin{cases} a_1 - a_2 = 1\\ 2a_2 + a_3 = -2\\ -a_1 + 2a_2 + 2a_3 = -5, \end{cases}$$

which solves to give $a_1 = 1$, $a_2 = 0$, and $a_3 = -2$. Thus

$$[L(\mathbf{v}_1)]_{\mathcal{C}} = \begin{bmatrix} 1\\0\\-2 \end{bmatrix}.$$

Next,

$$L(\mathbf{v}_2) = L\left(\begin{bmatrix}5\\2\end{bmatrix}\right) = \begin{bmatrix}2\\1\\-3\end{bmatrix}$$

We need the C-coordinates of $L(\mathbf{v}_2)$, so we find a_1, a_2, a_3 such that

$$a_1\mathbf{w}_1 + a_2\mathbf{w}_2 + a_3\mathbf{w}_3 = a_1\begin{bmatrix}1\\0\\-1\end{bmatrix} + a_2\begin{bmatrix}-1\\2\\2\end{bmatrix} + a_3\begin{bmatrix}0\\1\\2\end{bmatrix} = L(\mathbf{v}_2).$$

Like before, this yields a system of equations. We put its augmented matrix into row-echelon form:

$$\begin{bmatrix} 1 & -1 & 0 & | & 2 \\ 0 & 2 & 1 & | & 1 \\ -1 & 2 & 2 & | & -3 \end{bmatrix} \sim \begin{bmatrix} 1 & -1 & 0 & | & 2 \\ 0 & 2 & 1 & | & 1 \\ 0 & 1 & 2 & | & -1 \end{bmatrix} \sim \begin{bmatrix} 1 & -1 & 0 & | & 2 \\ 0 & 1 & 2 & | & -1 \\ 0 & 2 & 1 & | & 1 \end{bmatrix} \sim \begin{bmatrix} 1 & -1 & 0 & | & 2 \\ 0 & 1 & 2 & | & -1 \\ 0 & 0 & -3 & | & 3 \end{bmatrix}$$

which solves to give $a_1 = 3$, $a_2 = 1$, and $a_3 = -1$. Thus

$$[L(\mathbf{v}_2)]_{\mathcal{C}} = \begin{bmatrix} 3\\1\\-1 \end{bmatrix}.$$

The \mathcal{BC} -matrix of L is therefore

$$[L]_{\mathcal{BC}} = \left[\begin{bmatrix} L(\mathbf{v}_1) \end{bmatrix}_{\mathcal{C}} \quad \begin{bmatrix} L(\mathbf{v}_2) \end{bmatrix}_{\mathcal{C}} \right] = \begin{bmatrix} 1 & 3\\ 0 & 1\\ -2 & -1 \end{bmatrix}.$$

3a Find the characteristic polynomial:

$$P_{\mathbf{A}}(t) = \det(\mathbf{A} - t\mathbf{I}) = \begin{vmatrix} -t & 0 & 2 & 0 \\ 1 & -t & 1 & 0 \\ 0 & 1 & -2 - t & 0 \\ 0 & 0 & 0 & 1 - t \end{vmatrix} = (1 - t) \begin{vmatrix} -t & 0 & 2 \\ 1 & -t & 1 \\ 0 & 1 & -2 - t \end{vmatrix}$$
$$= (1 - t) \left[-t \begin{vmatrix} -t & 1 \\ 1 & -2 - t \end{vmatrix} + 2 \begin{vmatrix} 1 & -t \\ 0 & 1 \end{vmatrix} \right] = (1 - t)(t^3 + 2t^2 - t - 2)$$
$$= (t - 1)[t^2(t + 2) - (t + 2)] = (t - 1)(t + 2)(t^2 - 1) = (t - 1)^2(t + 1)(t + 2).$$

3b From above, we see that $P_{\mathbf{A}}(t) = 0$ if and only if t = -2, -1, 1, and so these are the eigenvalues of \mathbf{A} .

3c The smallest eigenvalue is -2. The corresponding eigenspace is

$$E_{\mathbf{A}}(-2) = \{ \mathbf{x} \in \mathbb{R}^4 : \mathbf{A}\mathbf{x} = -2\mathbf{x} \}.$$

Now, $A\mathbf{x} = -2\mathbf{x}$ is equivalent to $(\mathbf{A} + 2\mathbf{I})\mathbf{x} = \mathbf{0}$, which is a system of equations with augmented matrix

$$\begin{bmatrix} 2 & 0 & 2 & 0 & | & 0 \\ 1 & 2 & 1 & 0 & | & 0 \\ 0 & 1 & 0 & 0 & | & 0 \\ 0 & 0 & 0 & 3 & | & 0 \end{bmatrix}$$

From this we find that $x_4 = 0$, $x_2 = 0$, and $x_1 = -x_3$; that is, $\mathbf{x} \in E_{\mathbf{A}}(-2)$ if and only if

$$\mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} -x_3 \\ 0 \\ x_3 \\ 0 \end{bmatrix} = \begin{bmatrix} -1 \\ 0 \\ 1 \\ 0 \end{bmatrix} x_3$$

for some $x_3 \in \mathbb{R}$. Replacing x_3 with t, we therefore have

$$E_{\mathbf{A}}(-2) = \left\{ \begin{bmatrix} -1\\0\\1\\0 \end{bmatrix} t : t \in \mathbb{R} \right\}.$$

A basis for $E_{\mathbf{A}}(-2)$ is thus $\{[-1,0,1,0]^{\top}\}.$

3d The largest eigenvalue is 1. The corresponding eigenspace is

$$E_{\mathbf{A}}(1) = \{ \mathbf{x} \in \mathbb{R}^4 : \mathbf{A}\mathbf{x} = \mathbf{x} \}.$$

Now, $A\mathbf{x} = \mathbf{x}$ is equivalent to $(\mathbf{A} - \mathbf{I})\mathbf{x} = \mathbf{0}$, which is a system of equations with augmented matrix

$$\begin{bmatrix} -1 & 0 & 2 & 0 & | & 0 \\ 1 & -1 & 1 & 0 & | & 0 \\ 0 & 1 & -3 & 0 & | & 0 \\ 0 & 0 & 0 & 0 & | & 0 \end{bmatrix} \sim \begin{bmatrix} -1 & 0 & 2 & 0 & | & 0 \\ 0 & -1 & 3 & 0 & | & 0 \\ 0 & 1 & -3 & 0 & | & 0 \\ 0 & 0 & 0 & 0 & | & 0 \end{bmatrix} \sim \begin{bmatrix} -1 & 0 & 2 & 0 & | & 0 \\ 0 & -1 & 3 & 0 & | & 0 \\ 0 & 0 & 0 & 0 & | & 0 \\ 0 & 0 & 0 & 0 & | & 0 \end{bmatrix}$$

The last augmented matrix gives the system

$$\begin{cases} -x_1 + 2x_3 = 0\\ -x_2 + 3x_3 = 0 \end{cases}$$

Thus $x_1 = 2x_3$ and $x_2 = 3x_3$, where x_3 and x_4 are free. Replacing x_3 and x_4 with s and t, respectively, we have

$$E_{\mathbf{A}}(1) = \left\{ \begin{bmatrix} 2s\\3s\\s\\t \end{bmatrix} : s, t \in \mathbb{R} \right\} = \left\{ \begin{bmatrix} 2\\3\\1\\0 \end{bmatrix} s + \begin{bmatrix} 0\\0\\1\\1 \end{bmatrix} t : s, t \in \mathbb{R} \right\}$$
is thus

A basis for $E_{\mathbf{A}}(1)$ is thus

$$\left\{ \begin{bmatrix} 2\\3\\1\\0 \end{bmatrix}, \begin{bmatrix} 0\\0\\0\\1 \end{bmatrix} \right\}.$$