**1** We employ the same sequence of elementary row operations on both  $\mathbf{A}$  and  $\mathbf{I}_3$ , as follows.

$$\begin{bmatrix} 2 & 4 & 3 & | & 1 & 0 & 0 \\ -1 & 3 & 0 & | & 0 & 1 & 0 \\ 0 & 2 & 1 & | & 0 & 0 & 1 \end{bmatrix} \xrightarrow{r_2 \leftrightarrow r_1} \frac{1}{-r_1 \to r_1} \begin{bmatrix} 1 & -3 & 0 & | & 0 & -1 & 0 \\ 2 & 4 & 3 & | & 1 & 0 & 0 \\ 0 & 2 & 1 & | & 0 & 0 & 1 \end{bmatrix} \xrightarrow{r_2 \leftrightarrow r_3} \begin{bmatrix} 1 & -3 & 0 & | & 0 & -1 & 0 \\ 0 & 2 & 1 & | & 0 & 0 & 1 \end{bmatrix} \xrightarrow{r_2 \leftrightarrow r_3} \begin{bmatrix} 1 & -3 & 0 & | & 0 & -1 & 0 \\ 0 & 2 & 1 & | & 0 & 0 & 1 \end{bmatrix} \xrightarrow{r_2 \leftrightarrow r_3} \begin{bmatrix} 1 & -3 & 0 & | & 0 & -1 & 0 \\ 0 & 2 & 1 & | & 0 & 0 & 1 \end{bmatrix} \xrightarrow{r_2 \leftrightarrow r_3} \begin{bmatrix} 1 & -3 & 0 & | & 0 & -1 & 0 \\ 0 & 2 & 1 & | & 0 & 0 & 1 \end{bmatrix} \xrightarrow{r_2 \leftrightarrow r_3} \begin{bmatrix} 1 & -3 & 0 & | & 0 & -1 & 0 \\ 0 & 1 & 3 & | & 1 & 2 & 0 \end{bmatrix} \xrightarrow{-5r_2 + r_3 \to r_3}$$

$$\begin{bmatrix} 1 & -3 & 0 & | & 0 & -1 & 0 \\ 0 & 2 & 1 & | & 0 & 0 & 1 \\ 0 & 0 & -2 & | & 1 & 2 & -5 \end{bmatrix} \xrightarrow{\frac{1}{2}r_2 \to r_2} \begin{bmatrix} 1 & -3 & 0 & | & 0 & -1 & 0 \\ 0 & 1 & 1/2 & | & 0 & 0 & 1/2 \\ 0 & 0 & -2 & | & 1 & 2 & -5 \end{bmatrix} \xrightarrow{\frac{1}{4}r_3 + r_2 \to r_2} \begin{bmatrix} 1 & 0 & 0 & | & 3/4 & 1/2 & -9/4 \\ 0 & 1 & 0 & | & 3/4 & 1/2 & -9/4 \\ 0 & 1 & 0 & | & 1/4 & 1/2 & -3/4 \\ 0 & 0 & 1 & | & -1/2 & -1 & 5/2 \end{bmatrix} .$$

Therefore

$$\mathbf{A}^{-1} = \begin{bmatrix} 3/4 & 1/2 & -9/4 \\ 1/4 & 1/2 & -3/4 \\ -1/2 & -1 & 5/2 \end{bmatrix}.$$

To solve  $\mathbf{A}\mathbf{x} = \mathbf{b}$ , the idea is to simply use  $\mathbf{A}^{-1}$ :

$$\mathbf{A}\mathbf{x} = \mathbf{b} \quad \Rightarrow \quad \mathbf{x} = \mathbf{A}^{-1}\mathbf{b} = \frac{1}{4} \begin{bmatrix} 3 & 2 & -9\\ 1 & 2 & -3\\ -2 & -4 & 10 \end{bmatrix} \begin{bmatrix} 1\\ 0\\ 2 \end{bmatrix} = \frac{1}{4} \begin{bmatrix} -15\\ -5\\ 18 \end{bmatrix} = \begin{bmatrix} -15/4\\ -5/4\\ 9/2 \end{bmatrix}.$$

2 Let C denote the matrix. Then

**3** Here  $\mathbf{A}\mathbf{x} = \mathbf{b}$  with

$$\mathbf{A} = \begin{bmatrix} 2 & -1 & 1 \\ 1 & 3 & -2 \\ 4 & -3 & 1 \end{bmatrix}, \quad \mathbf{x} = \begin{bmatrix} x \\ y \\ z \end{bmatrix}, \quad \mathbf{b} = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}.$$

We have

$$\det(\mathbf{A}) = 2 \begin{vmatrix} 3 & -2 \\ -3 & 1 \end{vmatrix} - \begin{vmatrix} -1 & 1 \\ -3 & 1 \end{vmatrix} + 4 \begin{vmatrix} -1 & 1 \\ 3 & -2 \end{vmatrix} = 2(-3) - 2 + 4(-1) = -12,$$

and by Cramer's Rule,

$$x = \frac{1}{\det(\mathbf{A})} \begin{vmatrix} 1 & -1 & 1 \\ 0 & 3 & -2 \\ 2 & -3 & 1 \end{vmatrix} = -\frac{1}{12}(-5) = \frac{5}{12}$$
$$y = \frac{1}{\det(\mathbf{A})} \begin{vmatrix} 2 & 1 & 1 \\ 1 & 0 & -2 \\ 4 & 2 & 1 \end{vmatrix} = -\frac{1}{12}(1) = -\frac{1}{12}$$
$$z = \frac{1}{\det(\mathbf{A})} \begin{vmatrix} 2 & -1 & 1 \\ 1 & 3 & 0 \\ 4 & -3 & 2 \end{vmatrix} = -\frac{1}{12}(-1) = \frac{1}{12}.$$

The solution is therefore  $(x, y, z) = \left(\frac{5}{12}, -\frac{1}{12}, \frac{1}{12}\right)$ .

**4 A** is not invertible if and only if  $det(\mathbf{A}) = 0$ ; that is, we need

$$\begin{vmatrix} 7-\lambda & -15\\ 2 & -4-\lambda \end{vmatrix} = (7-\lambda)(-4-\lambda) - (-15)(2) = \lambda^2 - 3\lambda + 2 = 0,$$

which leads us to conclude that **A** is not invertible if and only if  $\lambda = 1, 2$ .

**5** The ranks of row-equivalent matrices are equal, and the rank of a matrix is easy to discern if it is in row-echelon form. Thus the way forward is to perform a succession of elementary row operations on **B** to obtain a matrix in just such a form:

$$\mathbf{B} \xrightarrow{-2r_1+r_2 \to r_2}_{-r_1+r_3 \to r_3} \xrightarrow{\left[ \begin{array}{cccc} 1 & 0 & 1 & 0 & 2\\ 0 & 1 & -1 & 1 & -1\\ 0 & 3 & -2 & 2 & 0\\ 0 & 3 & -2 & 2 & 0 \end{array} \right]} \xrightarrow{-r_3+r_4 \to r_4}_{-3r_2+r_3 \to r_3} \xrightarrow{\left[ \begin{array}{cccc} 1 & 0 & 1 & 0 & 2\\ 0 & 1 & -1 & 1 & -1\\ 0 & 0 & 1 & -1 & 3\\ 0 & 0 & 0 & 0 & 0 \end{array} \right]} = \mathbf{B}'$$

There are three nonzero rows in the row-echelon matrix  $\mathbf{B}'$ , so rank $(\mathbf{B}') = 3$ , and therefore rank $(\mathbf{B}) = 3$  also.

Now we determine the null space of **B**. By definition

$$\operatorname{Nul}(\mathbf{B}) = \{ \mathbf{x} : \mathbf{B}\mathbf{x} = \mathbf{0} \}.$$

Since **B**' is row-equivalent to **B**, the system of equations given by the matrix equation  $\mathbf{B}'\mathbf{x} = \mathbf{0}$  is equivalent to the system  $\mathbf{B}\mathbf{x} = \mathbf{0}$ , which is to say they have the same solution set. In fact we

may go further:

$$\mathbf{B}' \xrightarrow[-r_3+r_2 \to r_2]{}\xrightarrow{r_3+r_2 \to r_2} \left[ \begin{matrix} 1 & 0 & 0 & 1 & -1 \\ 0 & 1 & 0 & 0 & 2 \\ 0 & 0 & 1 & -1 & 3 \\ 0 & 0 & 0 & 0 & 0 \end{matrix} \right] = \mathbf{B}''.$$

The system  $\mathbf{B}''\mathbf{x} = \mathbf{0}$  has the same solution set as  $\mathbf{B}\mathbf{x} = \mathbf{0}$ , meaning  $\mathrm{Nul}(\mathbf{B}) = \mathrm{Nul}(\mathbf{B}'')$ . Unpacking  $\mathbf{B}''\mathbf{x} = \mathbf{0}$  gives

$$\begin{cases} x_1 + & x_4 - x_5 = 0\\ x_2 + & 2x_5 = 0\\ & x_3 - x_4 + 3x_5 = 0 \end{cases}$$

Letting  $x_4 = s$  and  $x_5 = t$ , we obtain  $x_1 = -s + t$ ,  $x_2 = -2t$ , and  $x_3 = s - 3t$ . Hence

$$\operatorname{Nul}(\mathbf{B}) = \left\{ \begin{bmatrix} -s+t\\ -2t\\ s-3t\\ s\\ t \end{bmatrix} : s, t \in \mathbb{R} \right\} = \left\{ s \begin{bmatrix} -1\\ 0\\ 1\\ 1\\ 0 \end{bmatrix} + t \begin{bmatrix} 1\\ -2\\ -3\\ 0\\ 1 \end{bmatrix} : s, t \in \mathbb{R} \right\}.$$

As for the range of  $\mathbf{B}$ , it is the set of all linear combinations of the column vectors of  $\mathbf{B}$ , or in other words the span of the column vectors:

$$\operatorname{Ran}(\mathbf{B}) = \operatorname{Span}\left\{ \begin{bmatrix} 1\\2\\1\\0 \end{bmatrix}, \begin{bmatrix} 0\\1\\3\\3 \end{bmatrix}, \begin{bmatrix} 1\\1\\-1\\-2 \end{bmatrix}, \begin{bmatrix} 0\\1\\2\\2 \end{bmatrix}, \begin{bmatrix} 2\\3\\2\\0 \end{bmatrix} \right\}.$$

**6** Ax = b has a unique solution if and only if **A** is invertible, and **A** is invertible if and only if det(**A**)  $\neq 0$ . Now,

$$\det(\mathbf{A}) \neq 0 \iff \begin{vmatrix} 1 & 2 & 0 \\ 5 & 1 & \lambda \\ 1 & -1 & 1 \end{vmatrix} \neq 0 \iff \lambda \neq 3.$$

Thus,  $\mathbf{A}\mathbf{x} = \mathbf{b}$  has a unique solution for any  $\mathbf{b} = \begin{bmatrix} 2 & 7 & \mu \end{bmatrix}^{\top}$  if and only if  $\lambda \neq 3$ , no matter what the value of  $\mu$  is.

In order to consider the possibility that  $\mathbf{A}\mathbf{x} = \mathbf{b}$  has no solution, we must first set  $\lambda = 3$ . Now we perform elementary row operations on the augmented of the resultant system:

$$\begin{bmatrix} 1 & 2 & 0 & | & 2 \\ 5 & 1 & 3 & | & 7 \\ 1 & -1 & 1 & | & \mu \end{bmatrix} \longrightarrow \begin{bmatrix} 1 & 2 & 0 & | & 2 \\ 0 & -9 & 3 & | & -3 \\ 0 & -3 & 1 & | & \mu - 2 \end{bmatrix} \longrightarrow \begin{bmatrix} 1 & 2 & 0 & | & 2 \\ 0 & -9 & 3 & | & -3 \\ 0 & 0 & 0 & | & \mu - 1 \end{bmatrix}.$$

From this we see that the system will have no solution if  $\mu \neq 1$ ; that is, the system is inconsistent if and only if  $\lambda = 3$ ,  $\mu \neq 1$ .

Finally, we see that the system will have infinitely many solutions if  $\mu = 1$ ; that is, the system is dependent if and only if  $\lambda = 3$  and  $\mu = 1$ .